

## More Power. Less Space. Easy Integration.

High-dynamic linear motor axes with patented Forceteq® force control - enhanced by high-torque hollow-shaft motors and web-based safety servocontrollers for unmatched efficiency.

## Jenny Science – a success story

As an ambitious, international family business, today Jenny Science is a leading component manufacturer in industrial automation. With over 70 employees at its headquarters in Rain, Switzerland, we design and manufacture compact linear motor axes, electric linear motor slides, hollow shaft servo motors and intelligent, web-based servo controllers for automation customers around the world.



### **2022** • «GO» and the axis moves!

INTAX°, the world's first linear motor axis with integrated servo drive; everything runs automatically: Simply connect the USB-C cable and enter «run.Webmotion» in Windows Explorer to open WebMotion°. Click on «GO» and the axis will start moving.



## **2015** • IHZ Innovation Award for Forceteg®

Jenny Science was selected for the IHZ Innovation Award for the Forceteq® force measuring technology, which senses forces in linear motor axes; executing movements and simultaneously monitoring them.



# 1998 Winner of Technology Location Switzerland for JENYTEC®

The ultra-compact and multi-functional JENYTEC® servo controllers are distinguished by the Technology Location panel of Switzerland. The product was selected for its compact construction and innovative content.

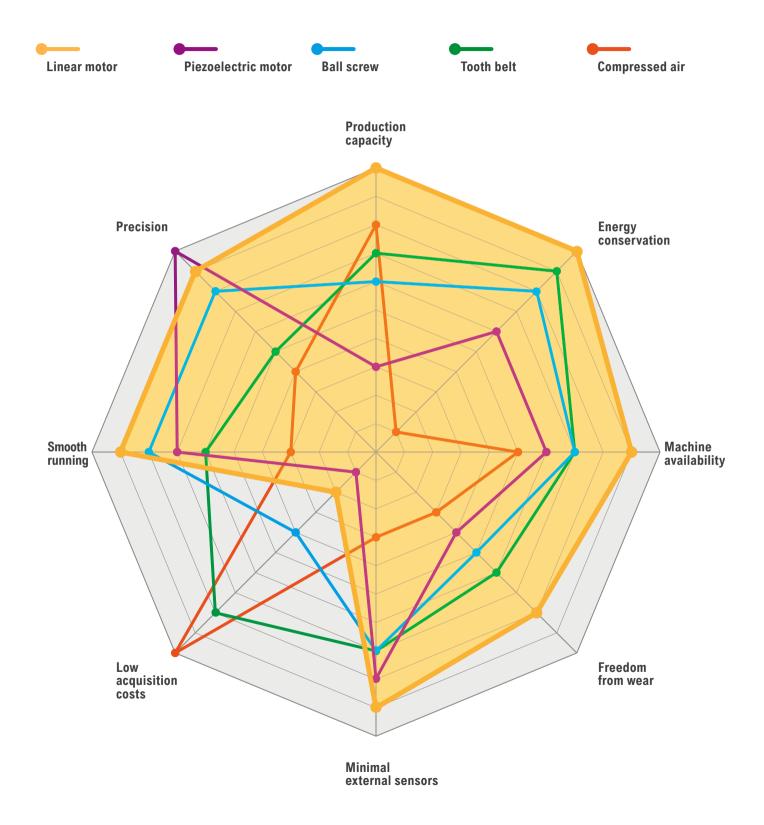


## **1994** ■ De Vigier Award for JENYMO®

Founder Alois Jenny wins the W.A. de Vigier foundation sponsorship award for the world's first bicycle dynamo with integrated standstill light. The JENYMO® bicycle dynamo has fully integrated standstill light electronics and a rechargeable battery.



## Various drive types for linear movements in comparison



## USPs of Linear and Rotary Motor Axes from Jenny Science

### Compact dimensions and lightweight construction

This allows you to build your machines smaller, saving space, especially with the INTAX® linear motor axis with integrated servo controller, thus achieving higher productivity within the same production area.

Especially for longer strokes, the installation space required for Jenny Science linear motor axes is very small in relation to the stroke. With the lightweight design, less mass is set in motion. This means shorter cycle times, less vibration, noise, and energy consumption.



### Modular construction kit for your standardization

Our flexible, well-designed modular system is truly unique in the market. With standardized linear and rotary motors from Jenny Science, you can build your automation systems more compactly, more lightweight, and in less time. This reduces costs in development, commissioning, and spare parts inventory.



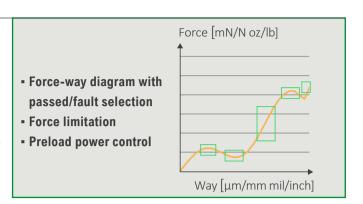
## Web browser operating menu

Simply enter the IP address in your web browser, and WebMotion® is ready to go. No software installation on your laptop or PC, and no registration required. Commissioning a servo axis has never been easier.



### Forceteq® force measurement technology

Forceteq® Basic is fully integrated into the XENAX® servo controller, measuring force via motor current. This simplifies setup, reduces costs, and enhances reliability by eliminating the need for a separate sensor. Forceteq® Pro uses an external DMS force sensor and the Signateq® measuring amplifier for precise measurements. It transfers force values directly to the XENAX® controller, ensuring high accuracy without needing an external evaluation box



### PLC bus communication

Easy integration of the market-leading Ethernet bus protocols such as EtherCAT, Profinet, Ethernet/IP, Powerlink and CANopen. With the supplied libraries, your machine programmers can work in the familiar development environment of the PLC and do not need any special knowledge. Furthermore, a complete ASCII command set is also available to operate the axes via the standard TCIP/IP socket or via COM interface.



### Automatic motor recognition

All Jenny Science linear and rotary axes are automatically recognized and parameterized by the XENAX® Servocontroller. Commissioning, testing and fine tuning are then performed using the intuitive, HTML 5-based WebMotion® operating menu and web browser. The programming for a possible «stand alone operation» is also carried out via web browser.



## Functional safety: SIL 2, PL d, Cat. 3

To guarantee the functional safety of the direct drive axes, the XENAX® Xvi 75V8S servo controller can be equipped with the Safety Motion Unit (SMU). This makes the various TÜV-certified safety functions STO, SS1, SS2 and SLS available. Furthermore, the axes can also be supplied in a UL certified version.





## XENAX® Xvi Servo controller

### Xvi 75V8S · Xvi 48V8

- · Easy commissioning and programming with WebMotion® via any HTML5 web browser
- · Automatic recognition and parameterization of JSc linear motor axes and servo motors
- · High-end control technology with continuous transition from position control to force control and vice versa
- · Interfaces and libraries for modern PLC Ethernet bus protocols
- · Safety functionalities certified according to TÜV, UL certified versions
- · Compact and everything inside: Safety, Web server, TCP/IP, Ethernet fieldbus modules, Master-Slave

Patented force monitoring Forceteq<sup>®</sup> basic (current-based) and Forceteq<sup>®</sup> pro (with strain gauge sensor)

Integrated web server with WebMotion® operator menu via HTML5 web browser

Position controller <-> force controller, S-curve trajectory generator

Xvi 75V8S: 12 digital inputs and 8 outputs with 24V Xvi 48V8: 4 digital inputs and 2 outputs with 24V

Fully programmable for stand-alone handling operations with Lead and Follower function up to 4 axes

Xvi 75V8S: separate power inputs for Logic (24V) and Power Stage (24V-75V) Xvi 48V8: separate power inputs for Logic (24V) and Power Stage (24V-48V)



## LINAX® Lxc Linear motor axes

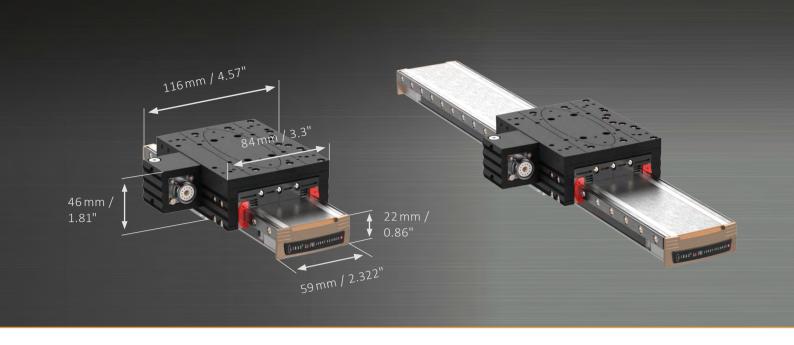
### Lxc = compact

- · Patented monoblock construction
- · No cables moving
- · Excellent performance/volume ratio
- · Safety integrity Level 2, PL d, CAT. 3 together with XENAX® servo drive

LINAX®	Position Accuracy [µm]		
Lve	optical 0.1	optical 1	
Lxc	+/- 0.5	+/- 1.5	

LINAX®	Stroke [mm] (in)	L Install. [mm] (in)	Force Fn/Fp [N] (lbf)	Weight Carriage /Total [g] (lbs)
Lxc 44F08 <sup>1)</sup>	44 (1.73)	78 (3.07)	8/24 (1.79/5.39)	130/350 (0.28/0.77)
Lxc 85F10 <sup>1)</sup>	85 (3.34)	144 (5.66)	10/30 (2.24/6.74)	230/650 (0.50/1.43)
Lxc 135F10	135 (5.31)	194 (7.63)	10/30 (2.24/6.74)	320/880 (0.70/1.94)
Lxc 230F10	230 (9.05)	290 (11.41)	10/30 (2.24/6.74)	450/1200 (0.99/2.64)
Lxc 80F40 <sup>1)</sup>	80 (3.14)	169 (6.65)	40/114 (8.99/25.62)	520/1470 (1.14/3.24)
Lxc 176F40 <sup>1)</sup>	176 (6.92)	265 (10.43)	40/114 (8.99/25.62)	750/2150 (1.65/4.73)
Lxc 272F40	272 (10.70)	361 (14.21)	40/114 (8.99/25.62)	1050/2800 (2.31/6.17)

 $<sup>^{1)}</sup>$  available with weight compensation of up to 3 kg (6.61 lbs)/6 kg (13.22 lbs)



## **NEW LINAX® Lxu F60S** Linear motor axes

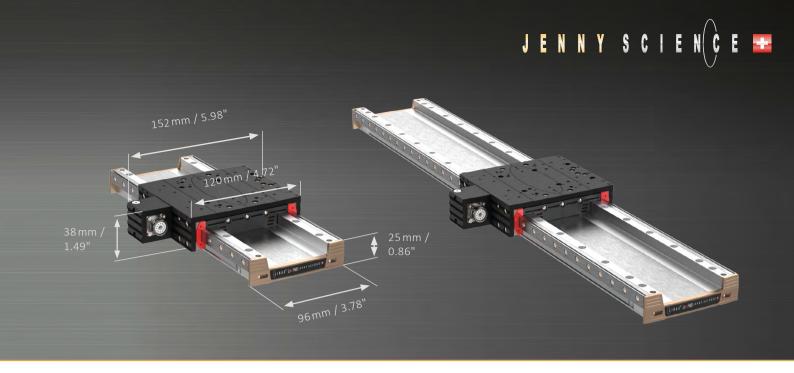
### Lxu = universal

- · Absolute measuring system
- · Single cable solution
- · 3 installation options: carriage/ground plate/front flange
- · 4 through holes for flexible installation
- $\cdot$  Safety Integrity Level 2, PL d, CAT. 3 together with XENAX  $^{\circ}$  servo controller

LINAX®	Force Fn/Fp [N] (lbf)	Weight Carriage [g] (lbs)	Р	osition Accura [µm]	су
Lyu FCOS	60/180	050 (2.00)	optical 0.1	optical 1	magnetic 1
Lxu F60S	(13.48/40.46)	950 (2.09)	+/- 0.5	+/- 1.5	+/- 2

LINAX®	Stroke [mm] (in)	L Install. [mm] (in)	Weight Total [g] (lbs)
Lxu 40F60S <sup>1)</sup>	40 (1.57)	170 (6.69)	1700 (3.74)
Lxu 80F60S <sup>1)</sup>	80 (3.14)	210 (8.26)	1900 (4.18)
Lxu 160F60S <sup>1)</sup>	160 (6.29)	290 (11.41)	2200 (4.85)
Lxu 240F60S	240 (9.44)	370 (14.56)	2600 (5.73)
Lxu 320F60S	320 (12.59)	450 (17.71)	2900 (6.39)

<sup>&</sup>lt;sup>1)</sup> available with weight compensation of up to 6 kg (13.22 lbs)



## **NEW LINAX® Lxs F60S** Linear motor axes

### Lxs = shuttle

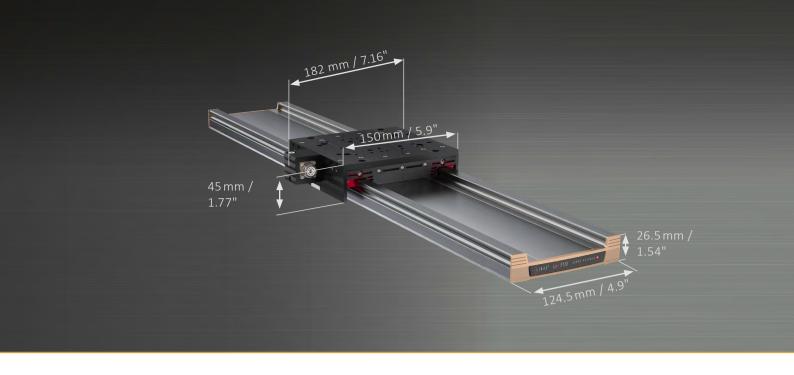
- · Absolute measuring system
- · Single cable solution
- · Long strokes up to 1600 mm (62.99 in)
- · Small height of only 38 mm (1.49 in)

- · Wide spaced linear guides for high loads
- · Safety Integrity Level 2, PL d, CAT. 3 together with XENAX® servo controller

LINAX®	Force Fn/Fp [N] (lbf)	Weight Carriage [g] (lbs)	Position Accuracy [µm]		су
Lvc FCOC	60/180	1000 (2.20)	optical 0.1	optical 1	magnetic 1
Lxs F60S	(13.48/40.46)	1000 (2.20)	+/- 0.5	+/- 1.5	+/- 2

LINAX®	Stroke [mm] (in)	L Install. [mm] (in)	Weight Total [g] (lbs)
Lxs 160F60S	160 (6.29)	290 (7.48)	2600 (5.73)
Lxs 200F60S	200 (7.87)	330 (12.99)	2800 (6.17)
Lxs 320F60S	320 (12.59)	450 (17.71)	3400 (7.49)
Lxs 400F60S	400 (15.74)	530 (20.86)	3900 (8.59)
Lxs 520F60S	520 (20.47)	650 (25.59)	4500 (9.92)
Lxs 600F60S	600 (23.62)	730 (28.74)	5000 (11.02)
Lxs 800F60S	800 (31.49)	930 (36.61)	6000 (13.22)
Lxs 1000F60S	1000 (39.37)	1130 (44.48)	7200 (15.87)
Lxs 1200F60S	1200 (47.24)	1330 (52.36)	8400 (18.51)
Lxs 1600F60S <sup>1)</sup>	1600 (62.99)	1730 (68.11)	10800 (23.80)

<sup>1)</sup> only available with magnetic measuring system



## LINAX® Lxs F120 Linear motor axes

### Lxs = shuttle

- · Absolute measuring system
- · Single cable solution

- · Long strokes up to 2000mm (78.74in)
- · The possibility of using multiple slides

LINAX®	Force Fn/Fp [N] (lbf)	Weight Carriage [g] (lbs)	Р	osition Accura [µm]	су
Lvc F120	120/300	2200 (5.07)	optical 0.1	optical 1	magnetic 1
Lxs F120	(27.0/67.4)	2300 (5.07)	+/- 0.5	+/- 1.5	+/- 2

LINAX®	Stroke [mm] (in)	L Install. [mm] (in)	Weight Total [g] (lbs)
Lxs 80F120	80 (3.15)	243 (9.57)	4700 (10.36)
Lxs 200F120	200 (7.87)	363 (14.29)	5900 (13.00)
Lxs 400F120	400 (15.75)	563 (22.17)	7800 (17.20)
Lxs 520F120	520 (20.47)	683 (26.89)	9000 (19.84)
Lxs 600F120	600 (23.62)	763 (30.04)	9800 (21.61)
Lxs 800F120	800 (31.50)	963 (37.91)	11800 (26.01)
Lxs 1000F120	1000 (39.37)	1163 (45.79)	13700 (30.20)
Lxs 1200F120	1200 (47.24)	1363 (53.66)	15700 (34.61)
Lxs 1600F120	1600 (62.99)	1763 (69.41)	19600 (43.21)
Lxs 2000F120	2000 (78.74)	2163 (85.16)	23500 (51.80)

<sup>1)</sup> available with weight compensation of up to 12 kg (26.46 lbs)



## **BERU 110V110J**

Cool Power: Efficient Brake Energy Recovery with the BERU!

### Reduced Energy Consumption

The new Brake Energy Recovery Unit (BERU) stores braking energy in capacitors and reuses it instead of converting it to heat. With the BERU, the axis saves energy.

## Compact, No Brake Resistors, No Heat

The BERU eliminates the need for traditional brake resistors, keeping the unit cool and requiring fewer capacitors.

### **Efficient Use of Capacitors**

What makes the BERU unique is its ability to discharge capacitors deeper and recharge them higher than the intermediate circuit voltage level. Specially developed, switched step-down and step-up regulators make this possible.

### Technological Highlights

- Intermediate Circuit Voltage: 24V - 110V DC
- Energy Storage: Max. 110 Joules
- · Connections:

1x Input from power supply min. 100V 30A 4x Power output 16A, XENAX\* 4x Logic output 24V 2A, XENAX\*



## **ELAX®** Ex Electric slides

### **ELAX®** Ex

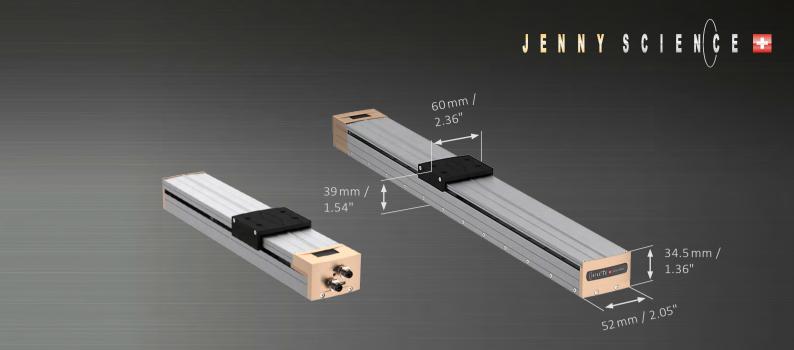
- · Single cable solution
- · Electric slides for fast, precise pick and place units
- · Modular design with direct fitting of axes on the front flange
- · Safety integrity level 2, PL d, Cat. 3 using XENAX® servo controller

ELAX®	Force Fn/Fp [N] (lbf)	Position Accuracy [µm]
Ex	20/60 (4.49/13.48)	+/- 5

ELAX®	Stroke [mm] (in)	L Install. min./max. [mm] (in)	Weight Carriage / Total [g] (lbs)
Ex 30F20 <sup>1)</sup>	30 (1.18)	109/139 (4.29/5.47)	195/560 (0.42/1.23)
Ex 50F20 <sup>1)</sup>	50 (1.96)	129/179 (5.08/7.05)	265/630 (0.58/1.38)
Ex 80F20 <sup>1)</sup>	80 (3.14)	177/257 (6.96/10.12)	340/780 (0.74/1.71)
Ex 110F20 <sup>1)</sup>	110 (4.33)	207/317 (8.15/12.48)	415/945 (0.91/2.08)
Ex 150F20	150 (5.90)	267/417 (10.51/16.42)	490/1110 (1.08/2.44)

<sup>1)</sup> available with spring-based weight compensation of up to 2 kg (4.40 lbs)

<sup>&</sup>lt;sup>1)</sup> available with magnetic weight compensation of up to 2.5 kg (5.51 lbs)



## INTAX® Tx Linear motor axis

### **INTAX®** = **Integrated Servo Controller**

- Integrated servo controller, motor wiring and cable chain
- $\cdot$  Absolute measurement system with 1µm resolution, no reference drive necessary
- · Two connectors only, one for Ethernet Bus and the other for 24V 36V DC-Power
- $\cdot$  No space is required in the control cabinet

INTAX®	Force Fn / Fp [N] (lbf)	Encoder absolute	Dimensions Carriage W x H [mm] (in)	Weight Carriage [g]	Repetition Accuracy [µm]
Tx	8/24 (1.80/5.40)	1μm abs.	60 x 39 (2.36 x 1.54)	170	+/- 2

INTAX®	Stroke [mm] (in)	L Install. [mm] (in)	Weight Total [g] (lbs)
Tx 50F08	50 (1.97)	149 (5.87)	425 (0.94)
Tx 100F08	100 (3.94)	201 (7.91)	550 (1.21)
Tx 200F08	200 (7.87)	299 (11.77)	800 (1.76)
Tx 400F08	400 (15.75)	500 (19.69)	1300 (2.87)
Tx 600F08	600 (23.62)	700 (27.56)	1800 (3.97)

## INTAX® Linear motor axes

## A milestone in miniaturization

### Introduction

The INTAX® linear motor axis pushes the boundaries of miniaturization and demonstrates what is technologically feasible today. It is the only solution on the market that integrates a fully integrated servo controller into a linear motor axis.

### What's behind it?

### · Plug & Play:

Connect the USB-C cable and open WebMotion® in the web browser.

#### · Immediate Start:

Click the «Quick Start» button and the axis moves. No download, no installation, no license codes.

### Technological Highlights

### · Integrated Servo Controller:

With a web server and an HTML5-based WebMotion® interface for easy and intuitive operation.

#### · Ethernet Fieldbus Communication:

Supports EtherCAT, Ethernet/IP, and Profinet.
Together with PLCopen® libraries, this allows for quick and seamless integration into your systems, saving valuable time.

### · Absolute Positioning:

The linear measurement system enables an immediate start without the need for homing, increasing efficiency and pro ductivity.

### **Design and Miniaturization**

### · Compact Design:

With a web server and an HTML5-based WebMotion® interface for easy and intuitive operation.

### · Space-saving:

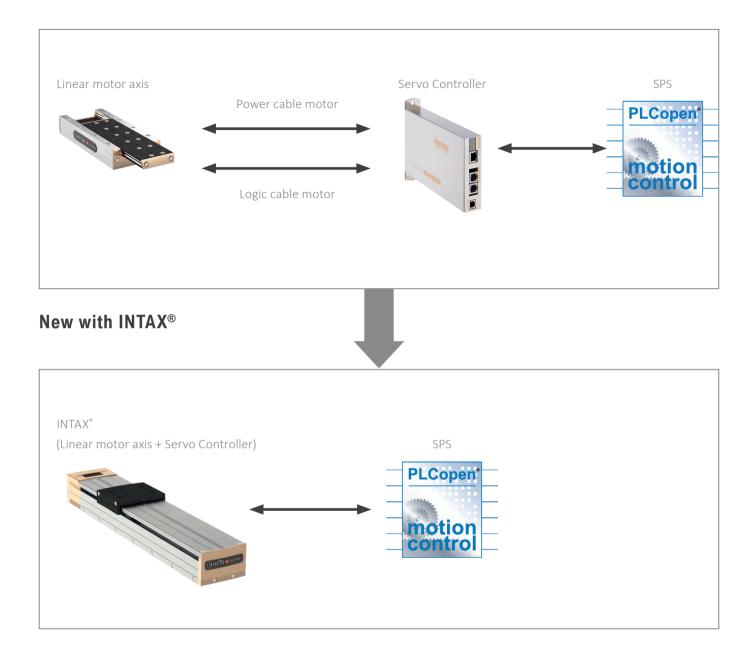
No additional wiring required, saving labor, costs and space.

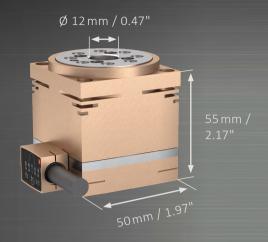
### Safety

### · STO Functionality:

In the event of a power stage interruption, communication is maintained as the power supply for the controller and power stage is separated.

## **Previously**





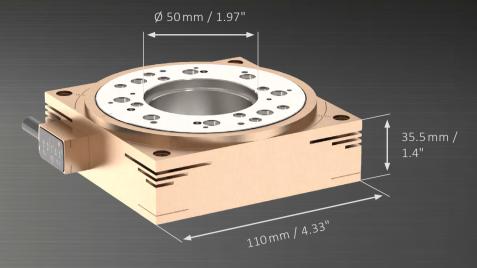
## ROTAX® Rxhq 50 Compact hollow shaft motor

- · Single cable solution
- · Ultra compact dimensions
- · Extra large through hollow shaft
- · High torque motor no gear

- · Integrated absolute encoder up to 2 592 000 Inc/rev
- · Multiturn with XENAX® Xvi 75V8S
- · Safety integrity level 2, PL d, Cat. 3 using XENAX® servo controller

ROTAX®	Length [mm] (in)	Dimensions W x H [mm] (in)	Hollow shaft opening [mm] (in)	Weight [g] (lbs)
Rxhq 50-12T0.3	50 (1.97)	50 x 55 (1.97 x 2.17)	12 (0.47)	440 (0.97)

Encoder absolute [Inc/rev]	Position Accuracy [arc-sec] Unidirect.   Bidirect.		Vmax 24V [rpm]	Vmax 48V [rpm]	Torque Mn/Mp [Nm] (lbf in)
120 000	+/- 6	+/- 11	500	1500	
162 000	+/- 2	+/- 10	500	1300	0.29/1.02 (2.57/9.03)
2 592 000	+/- 0.5	+/- 1	200		



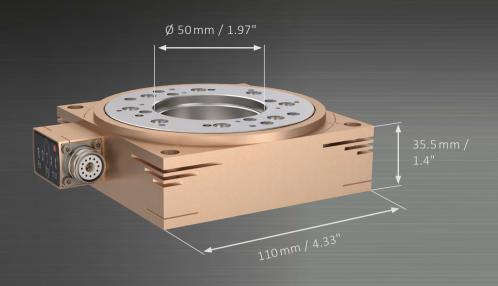
## ROTAX® Rxhq 110-50T1.5 Compact hollow shaft motor

- · Single cable solution
- · Ultra compact dimensions
- · Extra large through hollow shaft
- · High torque motor no gear

- · Integrated absolute encoder up to 2 592 000 Inc/rev
- · Multiturn with XENAX® Xvi 75V8S
- · Safety integrity level 2, PL d, Cat. 3 using XENAX® servo controller

ROTAX®	Length [mm] (in)	Dimensions W x H [mm] (in)	Hollow shaft opening [mm] (in)	Weight [g] (lbs)
Rxhq 110-50T1.5	110 (4.33)	110 x 35.5 (4.33 x 1.4)	50 (1.97)	1200 (2.65)

Encoder absolute [Inc/rev]	Position Accuracy [arc-sec] Unidirect.   Bidirect.		Vmax 24V [rpm]	Vmax 48V [rpm]	Torque Mn/Mp [Nm] (lbf in)
120 000	+/- 6	+/- 11	300	600	
648 000	+/- 2	+/- 4	300	600	1.5/4.0 (13.28/37.17)
2 592 000	+/- 0.5	+/- 1	200		



## ROTAX® Rxhq 110-50T1.5 M16 Compact hollow shaft motor

- · Single cable solution
- · Ultra compact dimensions
- $\cdot$  Extra large through hollow shaft
- · High torque motor no gear

- · Integrated absolute encoder up to 2 592 000 Inc/rev
- · Multiturn with XENAX® Xvi 75V8S
- · Safety integrity level 2, PL d, Cat. 3 using XENAX® servo controller

ROTAX®	Length [mm] (in)	Dimensions W x H [mm] (in)	Hollow shaft opening [mm] (in)	Weight [g] (lbs)
Rxhq 110-50T1.5	110 (4.33)	110 x 35.5 (4.33 x 1.4)	50 (1.97)	1200 (2.65)

Encoder absolute [Inc/rev]	Position Accuracy [arc-sec] Unidirect.   Bidirect.		Vmax 24V [rpm]	Vmax 48V [rpm]	Torque Mn/Mp [Nm] (lbf in)
120 000	+/- 6	+/- 11	300	600	
648 000	+/- 2	+/- 4	300	600	1.5/4.0 (13.28/37.17)
2 592 000	+/- 0.5	+/- 1	200		



## ROTAX® Rxhq 110-50T4.0 Compact hollow shaft motor

- · Single cable solution
- · Ultra compact dimensions
- · Extra large through hollow shaft
- · High torque motor no gear

- $\cdot$  Integrated absolute encoder up to 2 592 000  $\,$  Inc/rev
- · Multiturn with XENAX® Xvi 75V8S
- · Safety integrity level 2, PL d, Cat. 3 using XENAX® servo controller

ROTAX®	Length [mm] (in)	Dimensions W x H [mm] (in)	Hollow shaft opening [mm] (in)	Weight [g] (lbs)
Rxhq 110-50T4.0	110 (4.33)	110 x 55 (4.33 x 2.17)	50 (1.97)	2250 (4.96)

Encoder absolute [Inc/rev]	Position Accuracy [arc-sec] Unidirect.   Bidirect.		Vmax 24 V [rpm]	Vmax 48 V [rpm]	Vmax 72 V [rpm]	Torque Mn/Mp [Nm] (lbf in)
648 000	+/- 2	+/- 4	180	420	650	4.0/12.0
2 592 000	+/- 0.5	+/- 1		200		(35.4/106.2)



## **ROTAX® Rxvp** Rotary motor axes

### **Rxvp** = vacuum pressure

- · Single cable solution
- · Rotary motor axis with vacuum/compressed air feedthrough
- · Direct mounting on the ELAX® front flange
- · High level of accuracy and robustness

ROTAX®	Position Accuracy [arc-sec]			
Rxvp	Unidirect. +/- 12	Bidirect. +/- 20		

ROTAX®	Vmax [rpm]	Torque Mn/Mp [mNm] (lbf in)	Encoder incremental	Wiring
Rxvp 28-6T0.04	1500	40/110 (0.35/0.97)	64000 Inc/rev 360° endless rot.	One cable connection

ROTAX®	Shaft [mm] (in)	Length [mm] (in)	Dimensions W x H [mm] (in)	Weight Total Shaft 15/30 mm(0.59/1.18 in) [g] (lbs)
Rxvp	ø 6 x 15/ø 6 x 30	68	27.5 x 56.3	325/330
28-6T0.04	(ø 0.24 x 0.59/ø 0.24 x 1.18)	(2.68)	(1.08 x 2.22)	(0.71/0.72)
Rxvp	ø 6 x 15/ø 6 x 30	97.5	27.5 x 56.3	345/350
28-6T0.04 <sup>1)</sup>	(ø 0.24 x 0.59/ø 0.24 x 1.18)	(3.84)	(1.08 x 2.22)	(0.76/0.77)

 $<sup>^{1)}</sup>$  longer version for fitting to an ELAX $^{\circ}$  Ex F20 axis with weight compensation

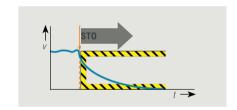


## **Safety Motion Unit (SMU)**

The optional SMU module extends the XENAX® Xvi 75V8S servo controller by TÜV certified safety functions (Safety Integrity Level 2, PL d, Cat. 3). The SMU modules are mounted and tested strictly in accordance with TÜV specifications, so that all safety functions can be guaranteed.

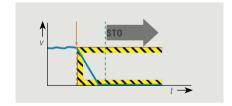
### **STO: Safe Torque Off**

The STO function is the most common and basic drive-integrated safety function. It ensures that no torque-generating energy can continue to act upon a motor.



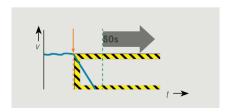
### SS1: Safe Stop 1

The SS1 function causes a motor to stop rapidly and safely and switches the motor to exert no torque at all after coming to a standstill, i.e. STO is activated.



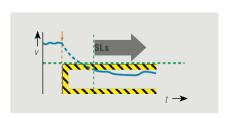
### SS2: Safe Stop 2

The SS2 function shuts down a motor quickly and safely and then activates the SOS function after coming to a standstill. With the SOS function, the stopped motor is brought into position and monitored by a drive control.



## **SLS: Safely-Limited Speed**

The SLS function ensures that the drive does not exceed a defined speed limit.



## PLC Bus communication

The XENAX® Xvi servo controllers can be operated via bus module with all market-leading PLC controls in real time. Libraries with application examples are available for the two practice-relevant operating modes, «profile positioning mode» and «cyclic synchronized positioning mode».

Programmable Logic Controller (PLC)



## **BECKHOFF**













**Bus Systems** 







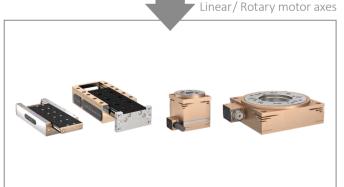




















## LINAX® Linear motor axes in clean room standards

### Cleanroom conditions according to ISO 14644-1

- · assembly is completed in a certified cleanroom (Class 7)
- · type of airflow: non laminar flow

LINAX® Linear motor axes (cross roll guides)	Slow	Typical	Fast
Velocity [m/s]	0.1	0.5	2.0
Accelerance [m/s²]	1.0	10.0	20.0
Air Cleanliness Class (according to ISO 14644-1)	3	5	5

LINAX® Linear motor axes (recirculating ball bearing guides)	Slow	Typical	Fast
Velocity [m/s]	0.1	0.5	2.0
Accelerance [m/s²]	1.0	10.0	20.0
Air Cleanliness Class (according to ISO 14644-1)	4	4	5

## Forceteq® basic

## Current-based force control with autonomous calibration



Forceteq® Basic offers a current-based force measurement technology that is seamlessly integrated into the XENAX® Xvi servo controller. No external sensors are required, enabling real-time monitoring and recording of force-displacement diagrams, leading to improved production quality and higher throughput.

### **Product Features**

### · Integration:

Fully integrated into the XENAX® Xvi servo controller.

#### · Calibration:

Self-calibrating motor, no external force sensors required.

### · Compatibility:

Suitable for all Jenny Science linear and rotary motor axes.

### · Programming:

Up to 10 force sectors programmable via Web-Motion\*.

### · Measurement Range:

0.5 - 180N

### **Benefits**

### · Quality Control:

Recording and logging of quality-relevant forcedisplacement diagrams.

### · Efficiency:

Immediate detection of errors and deviations, resulting in better quality and higher throughput.

### · Space Saving:

No additional inspection stations required.

## Forceteq® pro

## Precise force control has never been easier



Forceteq® Pro enables precise force measurements and control through the simple integration of standard strain gauge load cell with the Signateq® measuring amplifier. The high accuracy and efficiency of this technology save costs and improve production processes, eliminating the need for external evaluation electronics.

### **Product Features**

### · Easy Integration:

The Signateq® measuring amplifier allows the connection of commercially available strain gauge load cells from Burster, Kistler, or Futek and the adjustment of sensitivity.

### · High Precision:

Excellent linearity and accuracy of the strain gauge load cells with  $\leq$  0.5% precision.

### · Closed-loop force controller:

Force data is integrated into the XENAX $^{\circ}$  control loop and can be cyclically read by the PLC with a cycle time of up to 200 $\mu$ s. This enables continuous and timely monitoring as well as immediate response to changes.

### Installation

#### · Connect Sensor:

Solder four wires of the strain gauge load cell to the Signateq® measuring amplifier.

### Adjust Settings:

Enter the sensitivity value of the load cell in the «Load Cell» menu of the XENAX® Xvi 75V8S servo controller.

#### · Calibration:

Simply integrate calibration values from the sensor data-sheet or determine and input your own values and you're done.

## Benefits

2 2 2 2 2 1 ( E 1 ( 0 ) 1 Hz

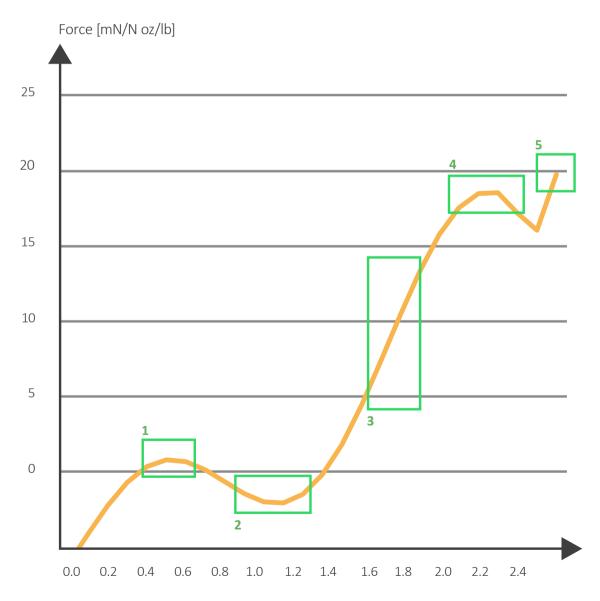
urrect force measurement in the XENAX® servo controller enables the shortest cycle times.

### Cost Savings

No external evaluation electronics required and direct integration into the PLC cycle for real-time monitoring and control.

#### Force Control:

Enables precise force control and measurement in the mN range during the production process.



Way [µm/mm mil/inch]



## X-Y Cross table

## LINAX® Lxs · LINAX® Lxc · INTAX® Tx

- · Extremely low overall height
- $\cdot$  Flatness of the whole area measurable and adjustable to < 10  $\mu m$

Arrangement	Axes	Function
X-Y LINAX®	1× LINAX <sup>®</sup> Lxc 44F08 1× LINAX <sup>®</sup> Lxc 44F08	X-axis Y-axis
X-Y LINAX®	1× LINAX® Lxs 400F60S 1× LINAX® Lxs 320F60S	X-axis Y-axis
X-Y INTAX®	1 × INTAX* Tx 100F08 1 × INTAX* Tx 100F08	X-axis Y-axis



## Y-Z Pick and Place · Z-R Handling

## ELAX® Ex · LINAX® Lxu · ROTAX® Rxvp

- · Vertical axis with weight compensation
- · With ELAX® adjustable with selection of spring assembly and with LINAX® adjustable with compressed air

Arrangement	Axes	Function
Y-Z flat	1× ELAX® Ex 30F20 1× ELAX® Ex 30F20 1× Weight comp. Ex 30F20 (0-2kg pull or push)	Y-axis — horizontal, flat Z-axis — vertical Compensation of payload
Z-R	1× LINAX° Lxu 80F60S 1× ROTAX° Rxvp 28-6T0.04 1× Weight comp. Lxu 80F60S (0-6kg)	Z-axis – vertical R-axis – rotative, vertical Compensation of payload



## X-Y-Z 3D Handling

### LINAX® Lxs/Lxu · ELAX® Ex

- · Consistent high level of accuracy thanks to low-maintenance and wear-free linear motor axes
- $\cdot$  Flexible dimensions selectable according to the size and weight of the product

Arrangement	Axes	Function
X-Y-Z flat	1× LINAX° Lxs 520F60S 1× LINAX° Lxu 320F60S 1× Cantilever armour to LINAX° Lxu 320F60S 1× LINAX° Lxu 80F60S 1× Weight comp. Lxu 80F60S (0-6kg)	X-axis — horizontal, flat Y-axis — horizontal, flat Reinforcement of Y-axis Z-axis — vertical Compensation of payload
X-Y-Z with ELAX®	1× LINAX® Lxu 520F60S 1× ELAX® Ex 80F20 1× ELAX® Ex 50F20 1× Weight comp. Ex 50F20 (0-2kg pull or push)	X-axis — horizontal, flat Y-axis — horizontal, flat Z-axis — vertical Compensation of payload



## R-Y-Z-R Pick and Place

## ELAX® Ex · ROTAX® Rxhq

- · Front flange on the slider is ideal for modular systems
- · Sophisticated, vertical cable and tube feedthrough for ROTAX® rotary motor axes

Arrangement	Axes	Function
R-Y-Z-R upright	1× ROTAX® Rxhq 110-50T4.0 1× ELAX® Ex 80F20 1× ELAX® Ex 30F20 1× Weight comp. Ex 30F20 (0-2kg pull or push) 1x ROTAX® Rxhq 50-12T0.3	R-axis — rotative, vertical Y-axis — horizontal, flat Z-axis — vertical Compensation of payload R-axis — rotative, vertical

## Weight Compensation

If the linear motor axis is used vertically, the slider should not fall when the power is switched off. Vertical weight compensation packages using compressed air or springs are available.



## X-Y-Z-R Gantry

## LINAX® Lxs · ELAX® Ex · ROTAX® Rxvp

• The Y-axes are arranged in an upright position, leading to minimal space requirement in relation to the strokes.

Arrangement	Axes	Function
X-Y-Z-R upright	1 x LINAX° Lxs 400F60S 2 x LINAX° Lxs 520F60S 3 x ELAX° Ex 50F20 3 x ROTAX° Rxvp 28-6T0.04 3 × Weight comp. Ex 50F20 (0-2kg pull or push)	X-axis Y-axis (Gantry) Z-axis R-axis Compensation of payload



## **Gantry**

## Components with Patented, Backlashfree Joint Bearing Technology

### Simple Setup

### · Pre-Assembled Bearing Joints:

Quick and easy assembly saves time and costs.

### · Main to Sub Position Adjustment:

Precise adjustment of the gantry structure is achieved by offsetting the SUB-Axis position to the MAIN-Axis position in the XENAX $^{\circ}$  servo controller with a resolution of 1 $\mu$ m.

### Technological Highlights

### · Backlashfree Rotary and Linear Joints:

Maximum precision and flexibility for both MAINand SUB-Axis.

### · No Stress:

Safe operation even with non-perfectly parallel installation.

# Carbon Fiber Carrier for High Precision in Temperature Variations

### · High Torsional Forces

Reduces deformation of the aluminum base plate during temperature fluctuations, ensuring constant precision.

### · Lightweight Design:

Shorter machine cycle times due to reduced weight.

### **Customer Benefits**

### · Cost Efficiency:

No need for complete systems; custom setups with our components are possible.

### · Time Savings:

Easy installation and quick commissioning.

### · Highest Precision:

Consistently accurate results, even with temperature fluctuations.

### · Efficiency Increase:

Faster production processes due to lighter components.

### JENNY SCIENCE AG (Corporate headquarters)

Sandblatte 11 CH-6026 Rain Phone +41 41 255 25 25 ramon.jenny@jennyscience.ch www.jennyscience.com

## Let's do business!

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#### SWITZERI AND

German speaking Jenny Science AG Sandblatte 11 CH-6026 Rain Phone +41 79 427 44 55 selcuk.cimenoglu@jennyscience.ch www.jennyscience.com

French speaking AxNum AG Solothurnstrasse 142 CH-2504 Biel/Bienne Phone +41 32 343 30 60 aebv@axnum.ch www.axnum.ch

#### **GERMANY**

Jenny Science GmbH DE-77652 Offenburg Phone +49 (0)160 501 42 21 josef.jogerst@jennyscience.de www.jennyscience.com

#### North-West

Dieter Hauck Phone +49 160 418 51 66 dieter.hauck@jennyscience.de

#### North-East

Robert Frank Phone +49 1 517 011 14 57 robert.frank@jennyscience.de

### South-West

Felix Hertweck Phone +49 1 515 218 33 80 felix.hertweck@jennyscience.de

#### South-East

Marcus Hartwagner Phone +49 1 515 547 76 33 marcus.hartwagner@jennyscience.de

### **FRANCE**

Liaison Office Jenny Science AG F-51100 Reims Phone +33 (0)6 40 24 42 13 frederic.menu@jennyscience.ch www.jennyscience.com

#### **AUSTRIA · HUNGARY**

next system Vertriebsges.m.b.H. Strobbonasse 4 A-1210 Wien Phone +43 1 33166 155 stephan.albrecht@nextsystem.at www.nextsystem.hu

#### ITALY

Smart Automation S.r.l. Via Redipuglia, 8 IT-20010 Bareggio (MI) Phone +39 02 902 60 226 massimiliano.manfredi@smartautomation.it www.smartautomation.it

#### **SWFDFN**

Servotronic AB Redaregatan 2 SE-731 24 Köping Phone +46 221 137 60 leif@servotronic.se www.servotronic.se

#### NETHERLANDS · BELGIUM

Conway Nederland BV De Greune 21a NL-7483 PH Haaksbergen Phone +31 53 574 32 39 sales@conwaynederland.nl www.conwaynederland.nl

#### SPAIN · PORTUGAL

AT Engineering S.L C\ Lope de Vega, 22-24 08005 Barcelona Phone +34 93.356.80.58 carlos.gordo@at-engineering.es www.at-engineering.es

#### **CHINA**

Beijing JingZhunBoDa Technology Co., Ltd. Room 515 East Wing, Donggang Xinzuo, No 56 Fuqian Road, Nanfaxin, Shunyi, Beijing, 101399 Phone +86 10 89492998 li.xin@bjjzbd.com www.bjjzbd.com

#### **SOUTH KOREA**

#C-802, 807, Gwangmyeong SK Techno Park, 60 Haan-ro, Gwangmyeong - si, Gyeonggi-do, South-Korea Phone +82 2 2083 1612 gh.choi@m2plus.kr www.m2plus.kr

#### **SINGAPORE**

Plant & Mill Supplies 4, Loyang Lane,#05-02 Singapore (508914) Phone +65 65 42 42 11 thteong@pmsupplies.com www.pmsupplies.com

#### MALAYSIA

Plant & Mill Motion Control Sdn Bhd Wisma Malvest, Room 2, 20C, Jalan Tun Dr. Awang 11900 Bayan Lepas, Penang Phone +604 645 1861, 644 8369 thteong@pmsupplies.com www.pmsupplies.com

#### THAILAND

PMC Technology Co., Lt 99/359 Moo.5, Tambon Bang Krang, Amphur Muang Nonthaburi, Nonthaburi 11000 Thailand Phone +66 2108-6041 thteong@pmsupplies.com www.pmc-technology.com

#### CANADA

Jenny Science US LLC 3337 Ivey Creek Road Maiden, NC 28650 Phone +1-828 417 0743 sales.us@jennyscience.com www.iennyscience.com

#### **MEXICO**

Jenny Science US LLC 3337 Ivey Creek Road Maiden, NC 28650 Phone +1-828 417 0743 sales.us@jennyscience.com www.jennyscience.com

#### **UNITED STATES OF AMERICA**

Jenny Science US LLC 3337 Ivey Creek Road Maiden, NC 28650 Phone +1-828 417 0743 sales.us@jennyscience.com www.jennyscience.com

### Arizona · California · Nevada Contour Motion, Inc.

357 Piercy Road San Jose, CA 95138 Phone +1-408 201 2345 raleigh@contourMotion.com www.contourmotion.com

#### Illinois · Wisconsin

Gaumond & Cella Inc. 150 S. Washington St. Suite A-11 Carpentersville, IL 60110 Phone +1-847 702 9506 ericv@g-c-inc.com www.q-c-inc.com

#### Minnesota · Wisconsin

Machine Automation Products 10744 Yellow Pine Street Coon Rapids, MN 55433 Phone +1-763 757 0198 awilliams@machineautomationproducts.net www.machineautomationproducts.net

#### Kentucky · Indiana

Blettner Engineering Co., Inc. 8919 Southeastern Ave Indianapolis, IN 46239 Phone +1-317 370 1319 trent@blettnerinc.com www.blettnerinc.com

**Tennessee · North & South Carolina** Martin Industrial Technology 10602 Mailey Road, Suite E & F Cornelius, NC 28031 Phone +1-704 885 2378 support@martinindtech.com www.martinindustrialtechnology.com



in www.linkedin.com/company/jennyscience



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